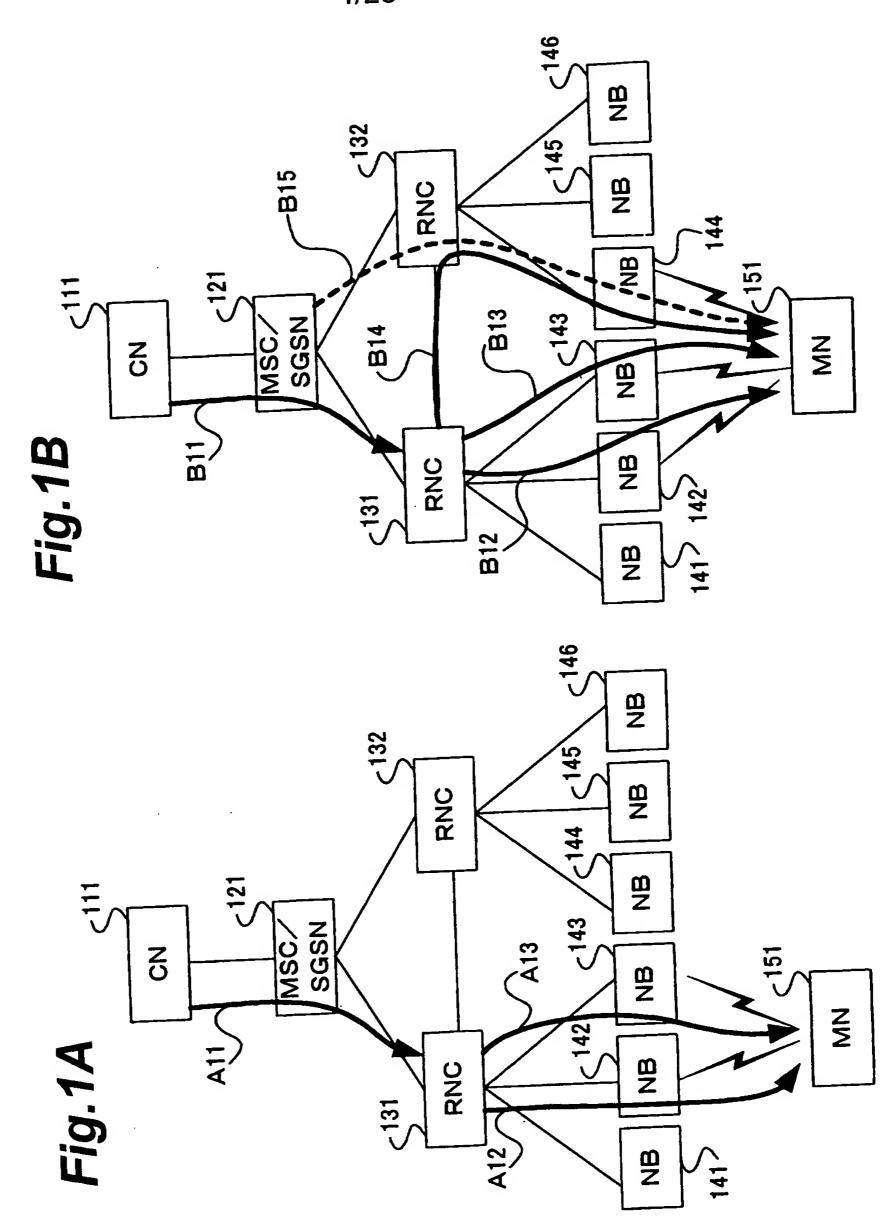
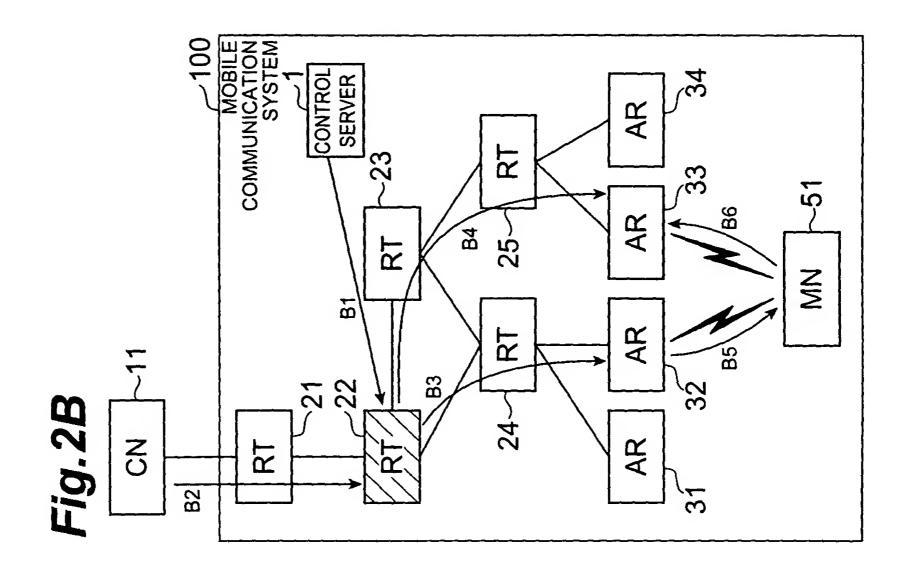
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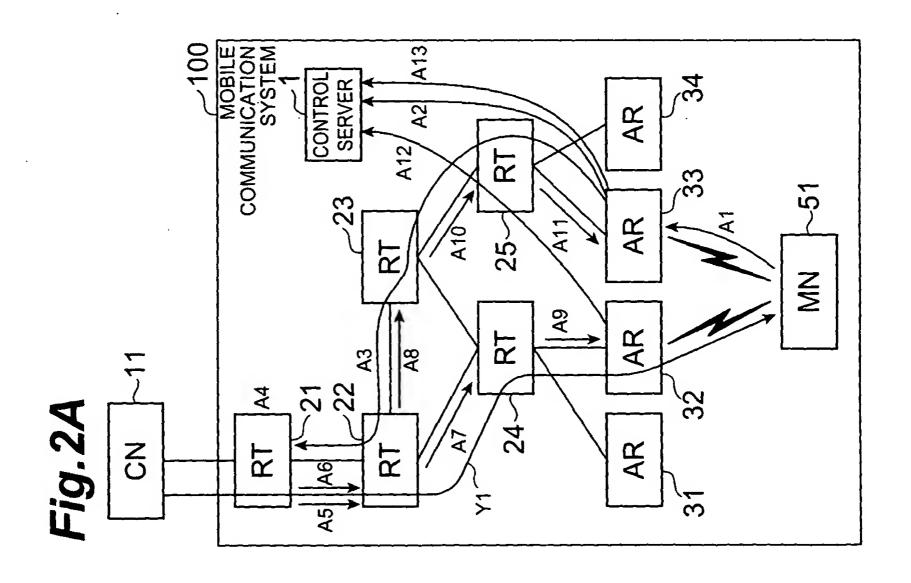


Fig.3

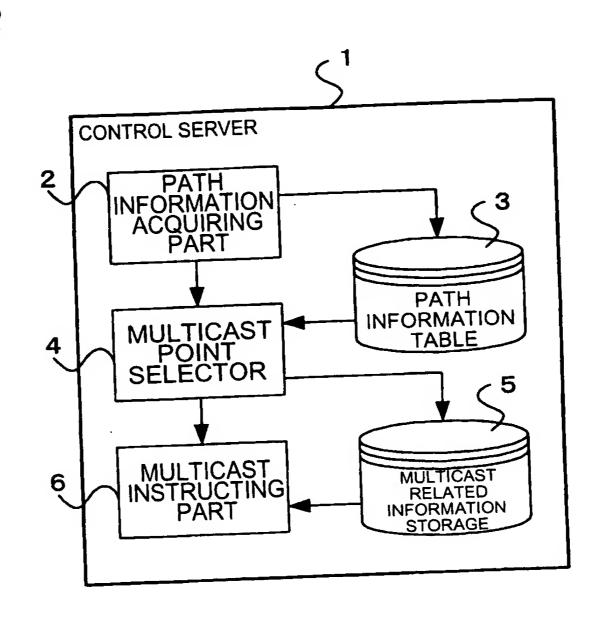
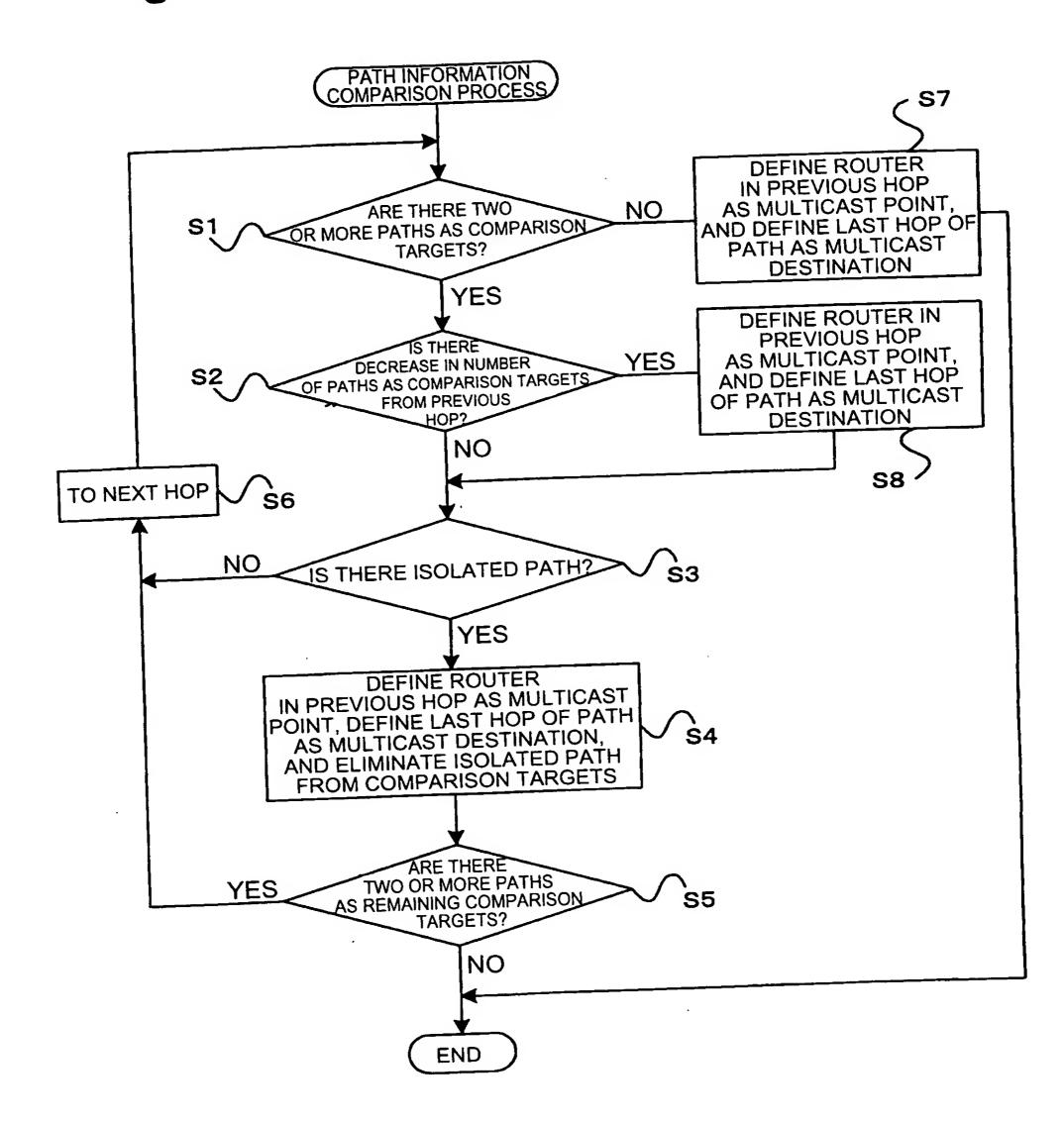


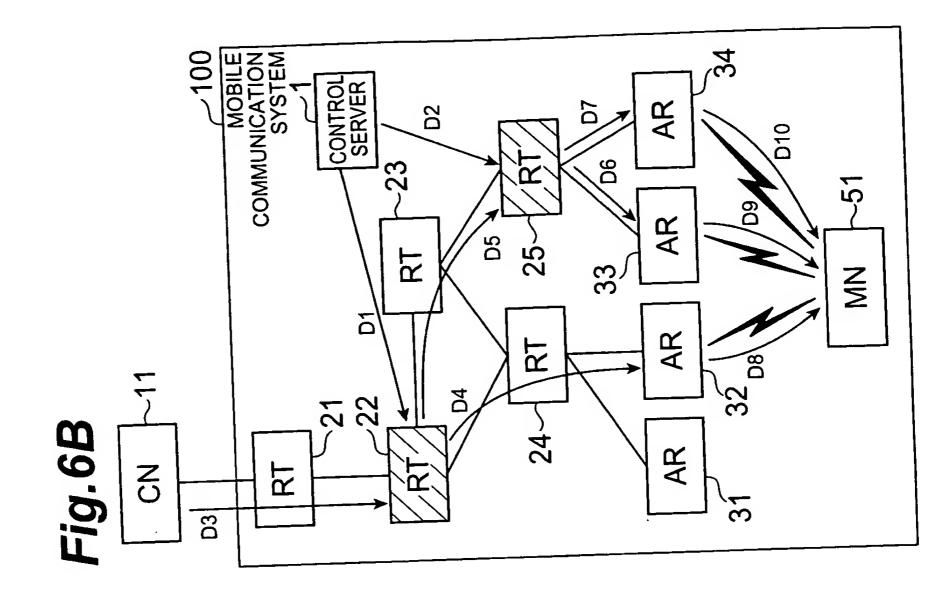
Fig.4

<u>3</u>				
	∫ 3a	\(\) 3b		
	Path 1 (end point: AR32)	Path 2 (end point: AR33)		
1st hop	RT21	RT21		
2nd hop	RT22	RT22		
3rd hop	RT24	RT23		
4th hop	AR32	RT25		
5th hop	-	AR33		

Fig.5



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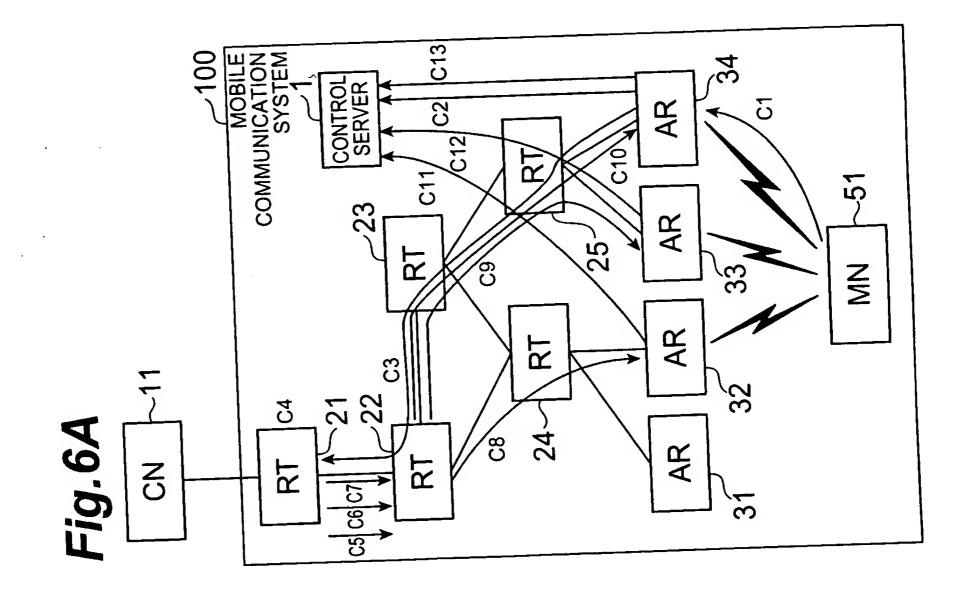
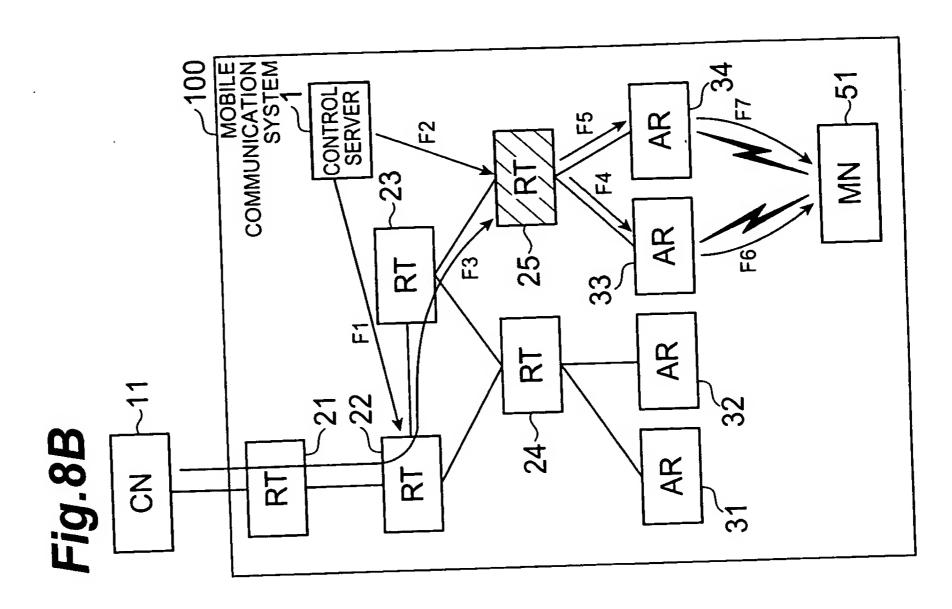


Fig.7

	<u>3</u>			
	/ 3a	/ 3b	/3c	
	5	5	5	
	Path 1 (end point: AR32)	Path 2 (end point: AR33)	Path 3 (end point: AR34)	
1st hop	RT21	RT21	RT21	
2nd hop	RT22	RT22	RT22	
3rd hop	RT24	RT23	RT23	
4th hop	AR32	RT25	RT25	
5th hop	· 	AR33	AR34	

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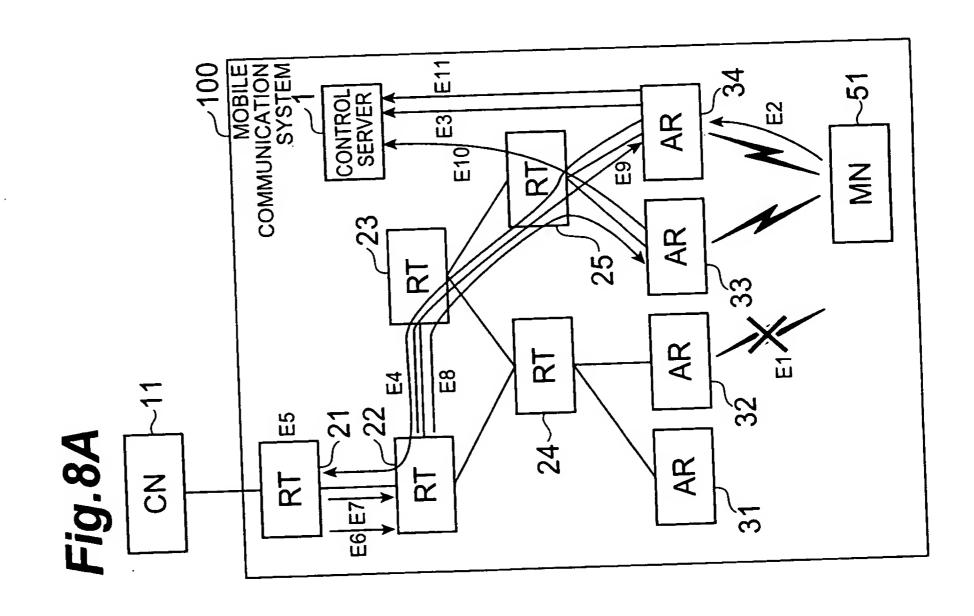
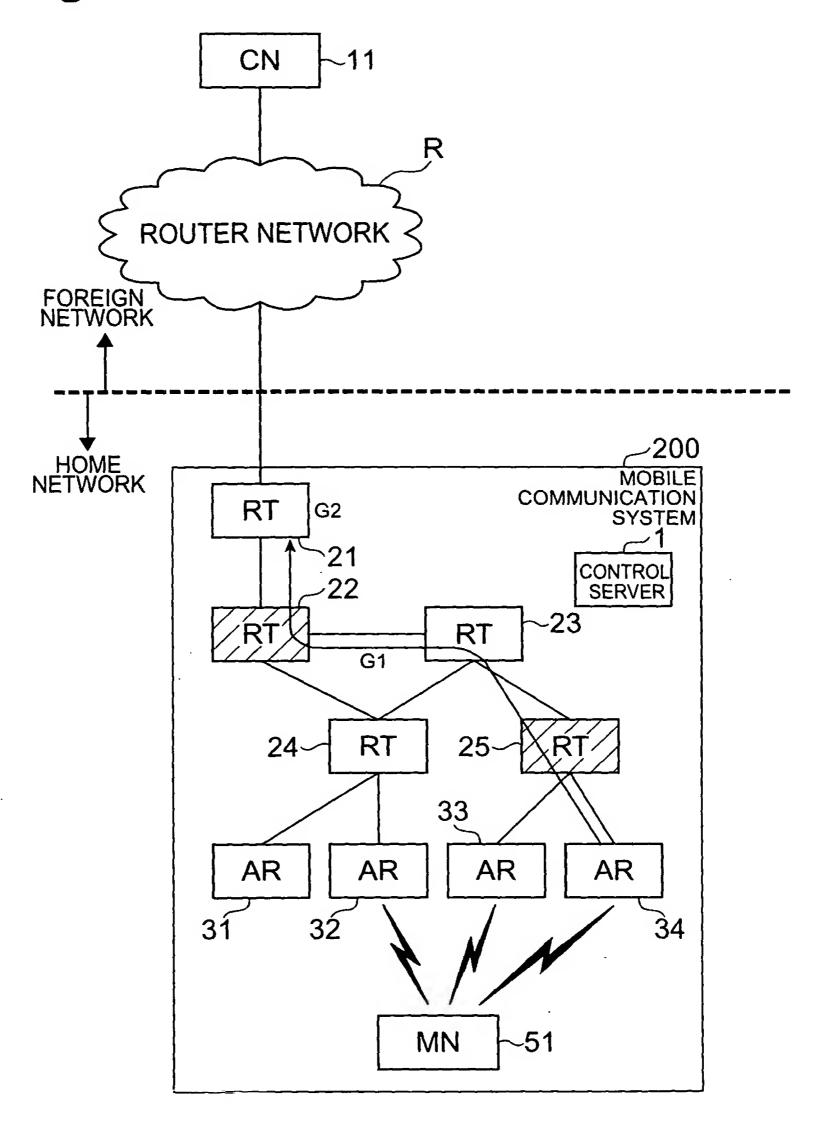


Fig.9

3				
	∠ 3b	\(\) 3c		
	Path 1 (end point: AR33)	Path 2 (end point: AR34)		
1st hop	RT21	RT21		
2nd hop	RT22	RT22		
3rd hop	RT23	RT23		
4th hop	RT25	RT25		
5th hop	AR33	AR34		

Fig.10

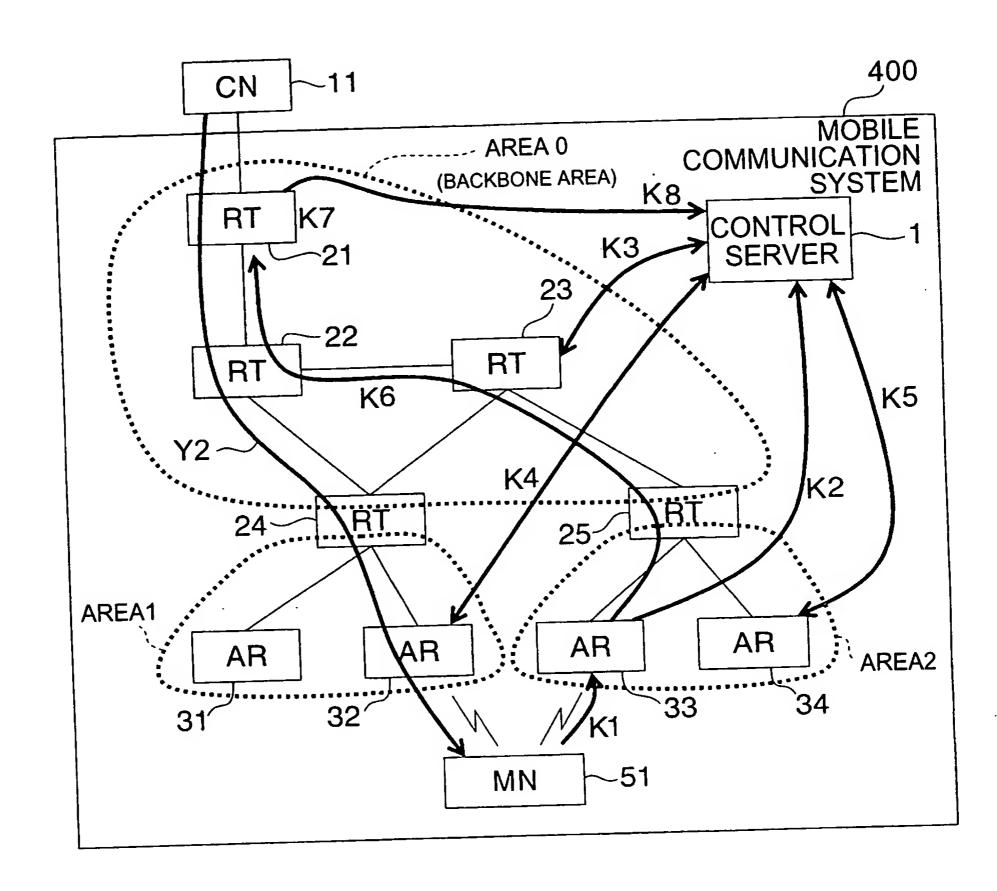


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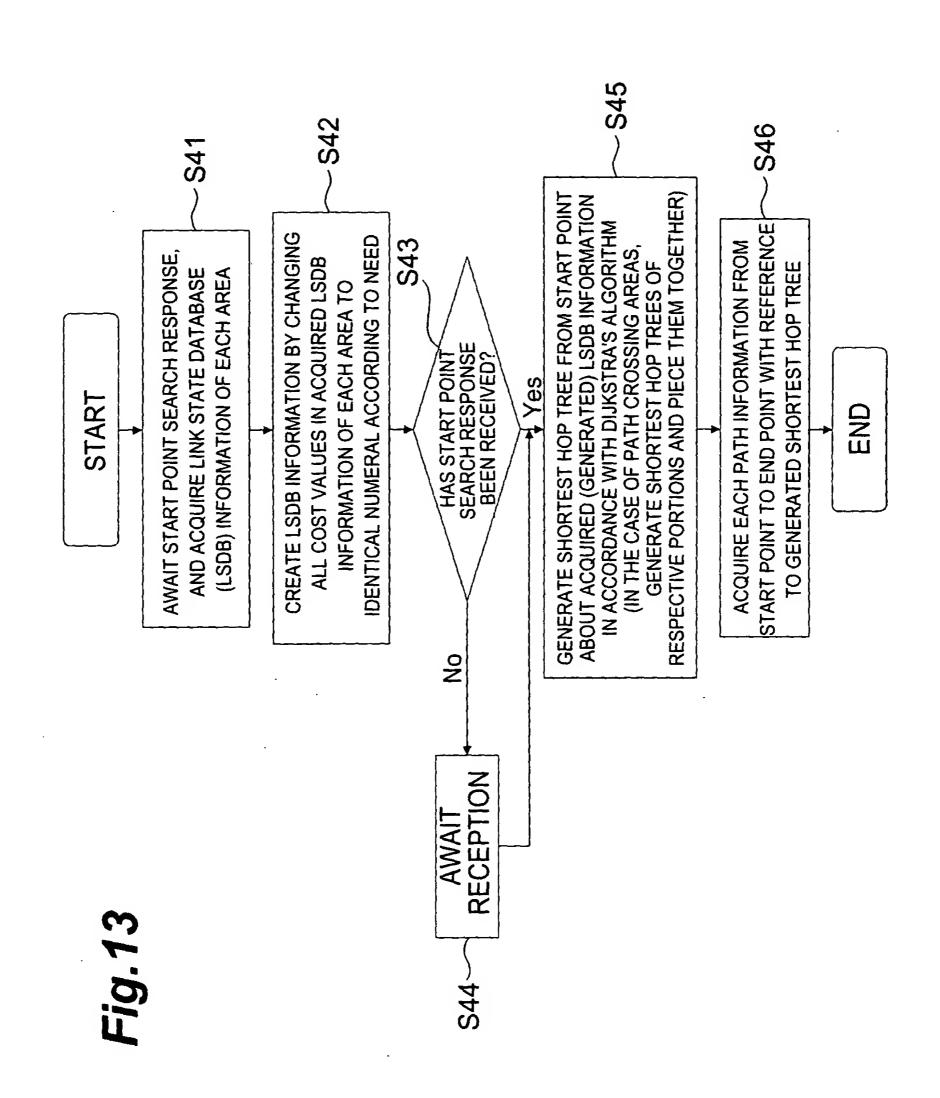
MOBILE COMMUNICATION SYSTEM CONTROL SERVER AR CS AR R 33 51 AR Fig.11B 21 Z 32 24 AR R 2 3

300 MOBILE COMMUNICATION SYSTEM $\frac{8}{1}$ CONTROL SERVER AR 42 R S AR 25 R 33/ 3 AR Fig. 11A ·21 ·22 Z Z AR R R

Fig.12



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RT25			X10	X11	
RT24		X8	6X		
RT23		X5		9X	X7
RT22	X2		X3	X4	
RT21		×			
From	RT21	RT22	RT23	RT24	RT25

Fig. 14A

AR32	X15		
AR31	X14		
RT24		X12	X13
To	RT24	AR31	AR32

AR34	X19		
AR33	X18		
RT25		X16	X17
From	RT25	AR33	AR34

Fig. 14C

Fig. 14B

RT25

RT24

RT23

RT22

RT21

From

T-

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Fig. 15A

-				
	AR32	-		
	AR31	-		
	RT24		-	-
	From	RT24	AR31	AR32

Fig. 15B

RT25

RT23

RT22

RT21

RT24

			
AR34	-		
AR33	-		
RT25		4-	-
From	RT25	AR33	AR34

Fig. 15C

Fig.16A

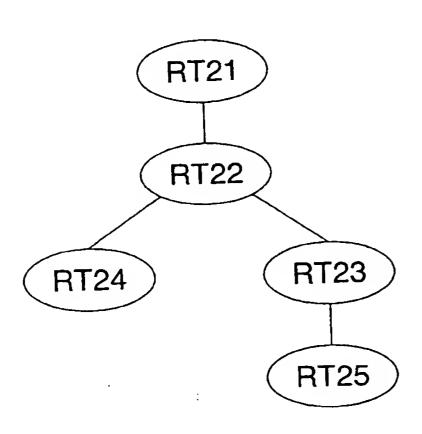


Fig.16B

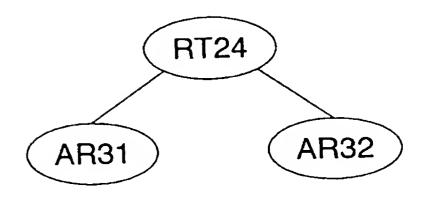
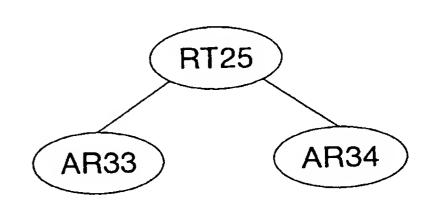


Fig.16C



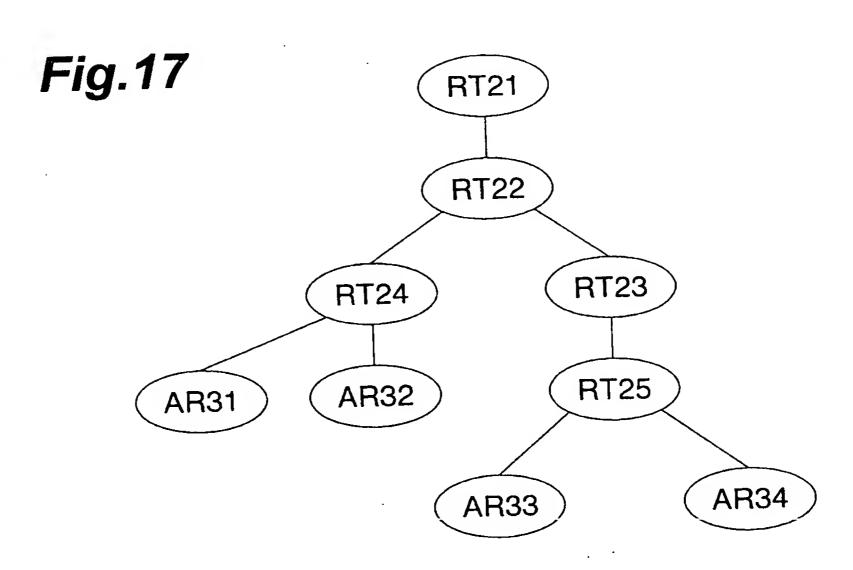


Fig.18

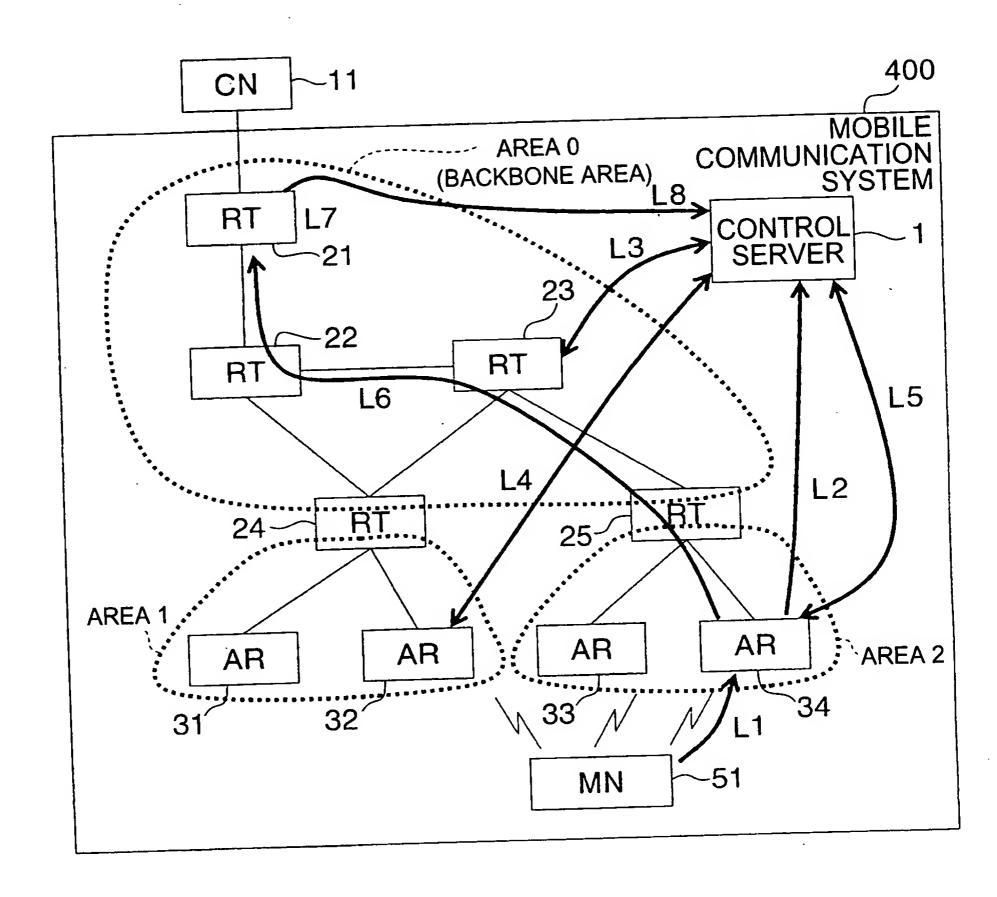


Fig.19

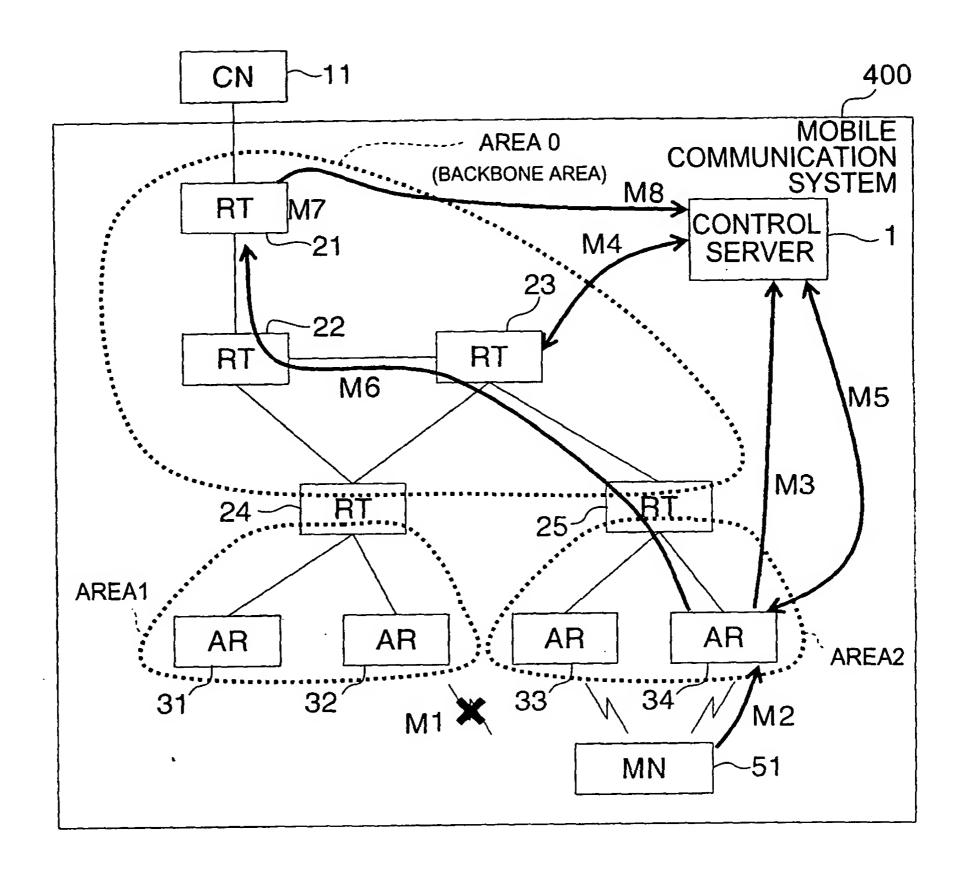


Fig. 20

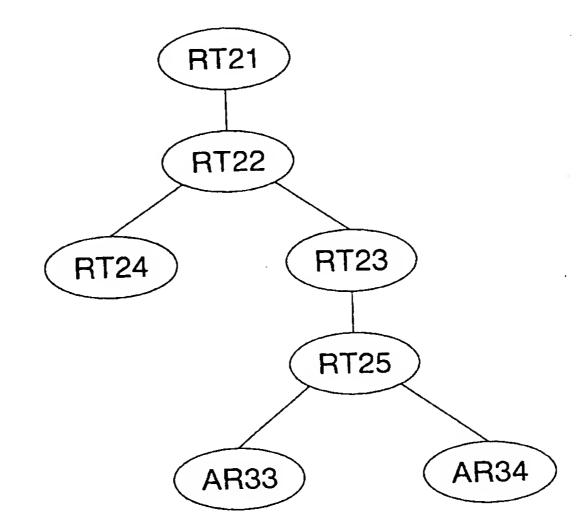
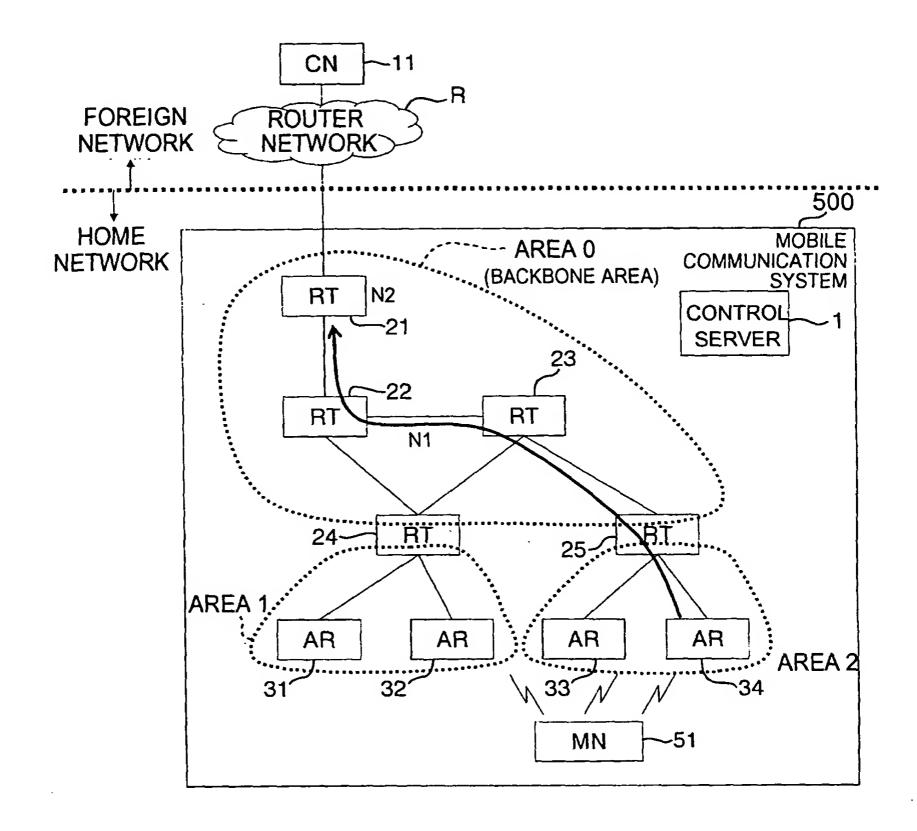
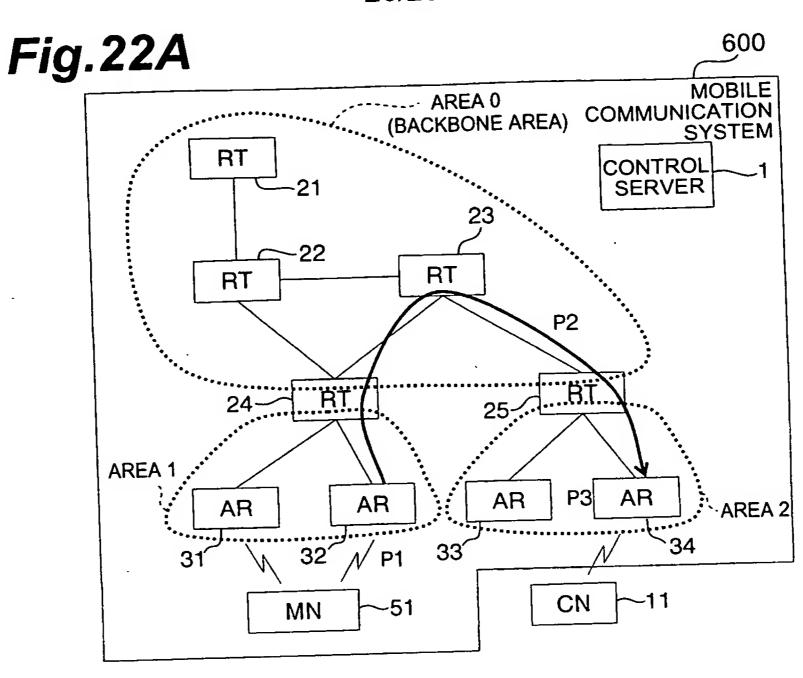


Fig.21



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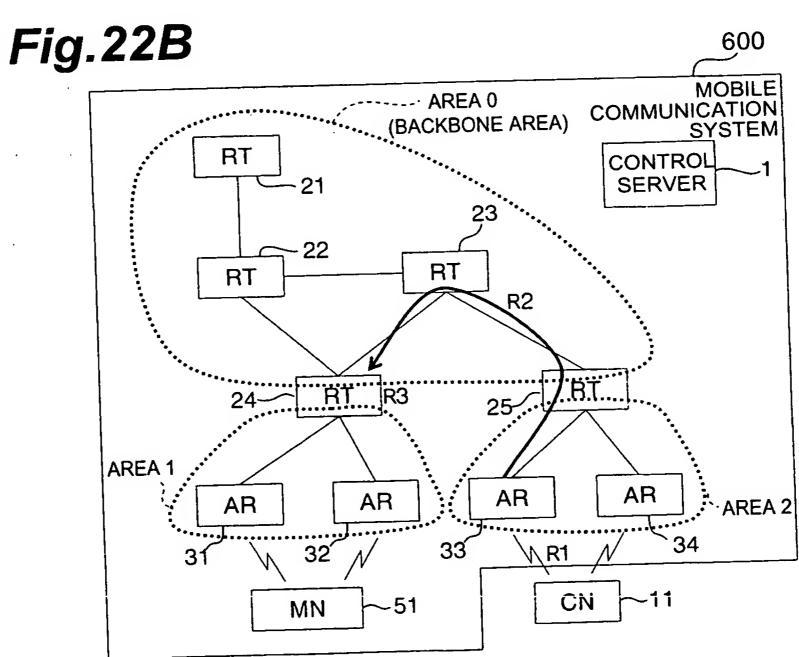


Fig.23A

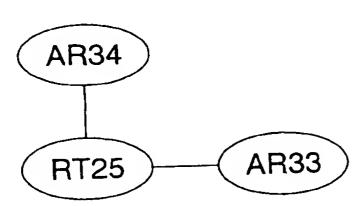


Fig.23C

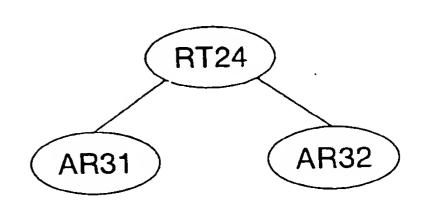


Fig.23B

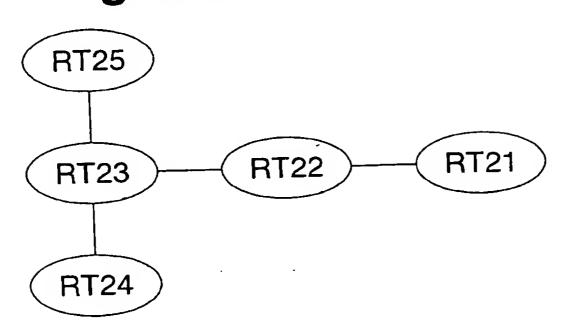
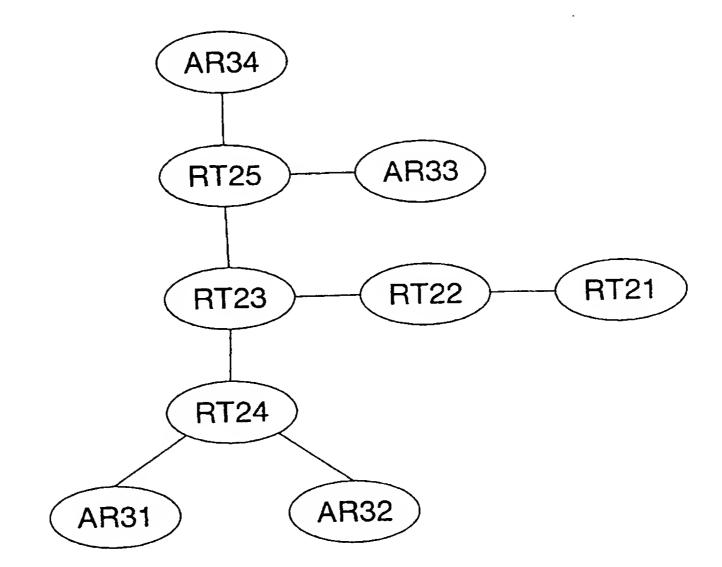


Fig.24



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